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Two-fluid modeling for low-pressure subcooled flow boiling

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Abstract

In the advanced electronic packaging, low-pressure subcooled flow boiling has been applied in design of compact heat exchangers for the effective electronic cooling. Through literature survey it is noted that little studies were carried out on the low-pressure and low-flow velocity subcooled flow boiling. In this paper a one-dimensional, non-equilibrium two-fluid model is proposed. The model has been validated with existing data in literature for both vertical up-flow and down-flow configurations. The simulated results show that under low-flow velocity the single phase heat transfer fraction is insignificant in vapor generation rate. The predicted results indicate that buoyancy force plays an important role on the void fraction evolvement, especially under low-flow velocity in vertical down-flow configuration. © 2005 Elsevier Ltd. All rights reserved.

Keywords: Subcooled flow boiling; Void fraction; Two-fluid; Vapor generation

1. Introduction

Subcooled boiling occurs when there is local boiling at the wall surface heated by the high heat fluxes, even though the bulk liquid has not reached the saturated temperature. The bubbles formed at the heated surface have a larger population density and short lifetime. Although the subcooled flow boiling improves the heat transfer, the pressure drop is increased such that the flow reduction and flow instability may occur. Fig. 1 shows the typical axial distribution of the temperature, void fraction, and bubble layer development along a uniformly heated channel, as illustrated by Srizawa and Kenning [1]. In the region of single-phase heat transfer, the temperature of the bulk liquid and the wall increases linearly along the tube. If the heating surface temperature exceeds the saturated temperature by a certain value, bubbles begin to initiate at a point called the onset of nucleation boiling (ONB, point A in Fig. 1), and they adhere and slide along the wall surface. The subcooled boiling continues downstream from ONB, due to the continuous wall heating. The bubble density increases and the bubble layer grows until the first bubble detaches from the heated surface into the core flow at point C. This low void fraction region continues until the void fraction starts to increase sharply at point D, the onset of significant void point (OSV). Finally the bulk liquid reaches to the saturated temperature.

In the advanced electronic packaging, low-pressure subcooled flow-boiling has been applied in the design of compact heat exchangers for the effective electronic

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Nomenclature

	(1,
а	thermal diffusivity, m/s
$a_{\rm G}$	sound speed of vapor, m/s
A	tube or annuli flow cross-section area, m ²
В	defined in Eq. (20)
С	defined in Eq. (21)
C_1	the portion of the heating surface not cov-
	ered by bubbles
C_2	coefficient related to the pumping factor,
	$C_2 = \frac{1}{1+\epsilon}$
C'	virtual mass coefficient
$C_{\rm D}$	drag coefficient for a single bubble
$C_{\rm FV}$	evaporation parameter with a value of
21	about 0.5
$C_{\rm EI}$	interfacial friction factor
	empirical coefficient in Eqs. (41) and (42)
$C_{\rm con}$	specific heat I/kg °C
d ₋	bubble departure diameter m
и _{ВА} Д	tube inside diameter, m
ש ח	hydraulia diameter $D = D$ for the tube
$D_{\rm h}$	invariance diameter, $D_{\rm h} - D$ for the engular
	channel, $D_{\rm h} = D_{\rm o} - D_{\rm i}$ for the annual
D	channel, m
$D_{\rm i}$	the outside diameter of the inner tube for the
P	annular channel, m
$D_{\rm o}$	the inside diameter of the out tube for the
	annular channel, m
fgo	single phase friction coefficient for vapor
$f_{\rm LO}$	single phase friction coefficient for liquid
$F_{\rm GI}$	interfacial force for the vapor due to the
	mass exchange, N/m ³
F_{LG}	interfacial force between the two phases, N/
	m ³
$F_{\rm LI}$	interfacial force for the liquid due to the
	mass exchange, N/m ³
F_{WG}	force between the wall surface and the
	vapor, N/m ³
$F_{\rm WL}$	force between the wall surface and the
	liquid, N/m^3
g	gravity acceleration, m/s^2
Ğ	mass flux flowing in the tube, kg/m^2s
h	enthalpy, J/kg
hic	evaporation heat from the liquid to the
	vapor. J/kg
\tilde{h}_{cm}	single phase heat transfer coefficient. W/
risp	$m^2 K$
Ia	Jacob number in terms of the liquid sub-
54	cooling $\rho_L C_{PL}(T_{sat}-T_L)$
K	thermal conductivity $W/m K$
I	length m
	length of single phase flow given in Eq. (50)
L_{sp}	total node points divided for the shares
IN Mar	Nusselt number defined in Heineum et al
$I v u_1$	inussen number denned in Hainoun et al.
	[13]

Nu_2	Nusselt number defined in Hainoun et al. [13]
Nu_{sp}	Nusselt number for single phase flow
Р	pressure, Pa
$P_{ m h}$	heating perimeter of the channel, m
Pr	Prandtl number
$q_{\rm L}$	heat flux component for the heating of the
-	liquid, W/m^2
$q_{\rm P}$	heat flux component due to the pumping
11	effect. W/m ²
<i>a</i> v	heat flux component for generation the
9 V	vapor on the wall surface W/m^2
an	total wall heat flux W/m^2
9 W R_	hubble radius m
	hubble Paynolds number
$Re_{\rm B}$	vonor Reynolds number accuming that the
Re _{GO}	vapor Reynolds humber assuming that the
D	whole mixture is nowing as vapor
Re_{LO}	liquid Reynolds number assuming that the
	whole mixture is flowing as liquid
t	time, s
Т	temperature, °C
$T_{W,ONB}$	wall temperature at the onset of nucleation
	boiling, °C
U	velocity, m/s
U_{GJ}	bubble relative velocity, m/s
X	vapor mass quality
x_{eq}	equilibrium thermodynamic quality
Y	defined in Eq. (19)
Y z	defined in Eq. (19) axial location along the flow direction, m
Y z	defined in Eq. (19) axial location along the flow direction, m
Y z Greek sy	defined in Eq. (19) axial location along the flow direction, m embols
Y z Greek sy α	defined in Eq. (19) axial location along the flow direction, m <i>imbols</i> void fraction
Y z Greek sy α α	defined in Eq. (19) axial location along the flow direction, m <i>mbols</i> void fraction void fraction at the onset of significant void
Y z Greek sy α α _{OSV} α _K	defined in Eq. (19) axial location along the flow direction, m mbols void fraction void fraction at the onset of significant void void fraction for phase K
Y z Greek sy α α _{OSV} α _K ε	defined in Eq. (19) axial location along the flow direction, m mbols void fraction void fraction at the onset of significant void void fraction for phase K pumping factor
Y z Greek sy α α_{OSV} α_{K} ε ε	defined in Eq. (19) axial location along the flow direction, m mbols void fraction void fraction at the onset of significant void void fraction for phase K pumping factor initial assumed void fraction at ONB
Y z Greek sy α α OSV α_{K} ε ε_{1} ε_{2}	defined in Eq. (19) axial location along the flow direction, m mbols void fraction void fraction at the onset of significant void void fraction for phase K pumping factor initial assumed void fraction at ONB initial assumed relative velocity at ONB
$\begin{array}{l} Y\\ z\\ Greek sy\\ \alpha\\ \alpha\\ \infty sv\\ \alpha_{K}\\ \varepsilon\\ \varepsilon_{1}\\ \varepsilon_{2}\\ u \end{array}$	defined in Eq. (19) axial location along the flow direction, m mbols void fraction void fraction at the onset of significant void void fraction for phase K pumping factor initial assumed void fraction at ONB initial assumed relative velocity at ONB dynamic viscosity. Pa s
$\begin{array}{l} Y\\ z\\ Greek sy\\ \alpha\\ \alpha\\ \alpha\\ \sigma\\ \sigma\\ \kappa\\ \varepsilon\\ \varepsilon_1\\ \varepsilon_2\\ \mu\\ \rho\end{array}$	defined in Eq. (19) axial location along the flow direction, m <i>mbols</i> void fraction void fraction at the onset of significant void void fraction for phase K pumping factor initial assumed void fraction at ONB initial assumed relative velocity at ONB dynamic viscosity, Pa s density, kg/m ³
$\begin{array}{l} Y\\ z\\ Greek sy\\ \alpha\\ \alpha\\ \sigma_{OSV}\\ \alpha_{K}\\ \varepsilon\\ \varepsilon_{1}\\ \varepsilon_{2}\\ \mu\\ \rho\\ \tau_{C}\end{array}$	defined in Eq. (19) axial location along the flow direction, m <i>mbols</i> void fraction void fraction at the onset of significant void void fraction for phase K pumping factor initial assumed void fraction at ONB initial assumed relative velocity at ONB dynamic viscosity, Pa s density, kg/m ³ condensation time, s
$\begin{array}{l} Y\\ z\\ Greek\ sy\\ \alpha\\ \alpha\\ \sigma\\ \sigma\\ \kappa\\ \varepsilon\\ \varepsilon_1\\ \varepsilon_2\\ \mu\\ \rho\\ \tau_C\\ \sigma\end{array}$	defined in Eq. (19) axial location along the flow direction, m <i>mbols</i> void fraction void fraction at the onset of significant void void fraction for phase K pumping factor initial assumed void fraction at ONB initial assumed relative velocity at ONB dynamic viscosity, Pa s density, kg/m ³ condensation time, s surface tension N/m
Y z Greek sy α α _{OSV} α _K ε ε ε ε ε ε 2 μ ρ τ _C σ Γ	defined in Eq. (19) axial location along the flow direction, m <i>mbols</i> void fraction void fraction at the onset of significant void void fraction for phase K pumping factor initial assumed void fraction at ONB initial assumed relative velocity at ONB dynamic viscosity, Pa s density, kg/m ³ condensation time, s surface tension, N/m vapor or liquid generation rate per unit mix-
Y z Greek sy α α _{OSV} α _K ε ε ₁ ε ₂ μ ρ τ _C σ Γ	defined in Eq. (19) axial location along the flow direction, m <i>mbols</i> void fraction void fraction at the onset of significant void void fraction for phase K pumping factor initial assumed void fraction at ONB initial assumed relative velocity at ONB dynamic viscosity, Pa s density, kg/m ³ condensation time, s surface tension, N/m vapor or liquid generation rate per unit mix- ture volume. kg/m ³ s
Y z $Greek sy \alpha \alpha_{OSV} \alpha_{K} \varepsilon \varepsilon_{1} \varepsilon_{2} \mu \rho \tau_{C} \sigma \Gamma \Gamma$	defined in Eq. (19) axial location along the flow direction, m <i>mbols</i> void fraction void fraction at the onset of significant void void fraction for phase K pumping factor initial assumed void fraction at ONB initial assumed relative velocity at ONB dynamic viscosity, Pa s density, kg/m ³ condensation time, s surface tension, N/m vapor or liquid generation rate per unit mix- ture volume, kg/m ³ s vapor condensation rate in the bulk core
$\begin{array}{l} Y\\ z\\ Greek\ sy\\ \alpha\\ \alpha_{OSV}\\ \alpha_{K}\\ \varepsilon\\ \varepsilon_{1}\\ \varepsilon_{2}\\ \mu\\ \rho\\ \tau_{C}\\ \sigma\\ \Gamma\\ \Gamma\\ \Gamma_{G,con} \end{array}$	defined in Eq. (19) axial location along the flow direction, m <i>mbols</i> void fraction void fraction at the onset of significant void void fraction for phase K pumping factor initial assumed void fraction at ONB initial assumed relative velocity at ONB dynamic viscosity, Pa s density, kg/m ³ condensation time, s surface tension, N/m vapor or liquid generation rate per unit mix- ture volume, kg/m ³ s vapor condensation rate in the bulk core, ha/m ³ s
$\begin{array}{l} Y\\ z\\ Greek\ sy\\ \alpha\\ \alpha_{OSV}\\ \alpha_{K}\\ \varepsilon\\ \varepsilon_{1}\\ \varepsilon_{2}\\ \mu\\ \rho\\ \tau_{C}\\ \sigma\\ \Gamma\\ \Gamma\\ \Gamma_{G,con}\\ \Gamma\end{array}$	defined in Eq. (19) axial location along the flow direction, m <i>mbols</i> void fraction void fraction at the onset of significant void void fraction for phase K pumping factor initial assumed void fraction at ONB initial assumed relative velocity at ONB dynamic viscosity, Pa s density, kg/m ³ condensation time, s surface tension, N/m vapor or liquid generation rate per unit mix- ture volume, kg/m ³ s vapor condensation rate in the bulk core, kg/m ³ s
$\begin{array}{l} Y\\ z\\ Greek \ sy\\ \alpha\\ \alpha_{OSV}\\ \alpha_{K}\\ \varepsilon\\ \varepsilon_{1}\\ \varepsilon_{2}\\ \mu\\ \rho\\ \tau_{C}\\ \sigma\\ \Gamma\\ \Gamma\\ G, con\\ \end{array}$	defined in Eq. (19) axial location along the flow direction, m <i>mbols</i> void fraction void fraction at the onset of significant void void fraction for phase K pumping factor initial assumed void fraction at ONB initial assumed relative velocity at ONB dynamic viscosity, Pa s density, kg/m ³ condensation time, s surface tension, N/m vapor or liquid generation rate per unit mix- ture volume, kg/m ³ s vapor condensation rate in the bulk core, kg/m ³ s
$\begin{array}{l} Y\\ z\\ Greek \ sy\\ \alpha\\ \alpha_{OSV}\\ \alpha_{K}\\ \varepsilon\\ \varepsilon_{1}\\ \varepsilon_{2}\\ \mu\\ \rho\\ \tau_{C}\\ \sigma\\ \Gamma\\ \Gamma\\ \Gamma_{G,Con}\\ \Gamma\\ \Gamma_{G,V}\\ \Gamma\end{array}$	defined in Eq. (19) axial location along the flow direction, m <i>mbols</i> void fraction void fraction at the onset of significant void void fraction for phase K pumping factor initial assumed void fraction at ONB initial assumed relative velocity at ONB dynamic viscosity, Pa s density, kg/m ³ condensation time, s surface tension, N/m vapor or liquid generation rate per unit mix- ture volume, kg/m ³ s vapor condensation rate in the bulk core, kg/m ³ s vapor production rate by the wall heating, kg/m ³ s
$\begin{array}{l} Y\\ z\\ Greek \ sy\\ \alpha\\ \alpha_{OSV}\\ \alpha_{K}\\ \varepsilon\\ \varepsilon_{1}\\ \varepsilon_{2}\\ \mu\\ \rho\\ \tau_{C}\\ \sigma\\ \Gamma\\ \Gamma\\ G, con\\ \Gamma\\ G, V\\ \Gamma_{G, net} \end{array}$	defined in Eq. (19) axial location along the flow direction, m <i>mbols</i> void fraction void fraction at the onset of significant void void fraction for phase K pumping factor initial assumed void fraction at ONB initial assumed relative velocity at ONB dynamic viscosity, Pa s density, kg/m ³ condensation time, s surface tension, N/m vapor or liquid generation rate per unit mix- ture volume, kg/m ³ s vapor condensation rate in the bulk core, kg/m ³ s vapor production rate by the wall heating, kg/m ³ s
$\begin{array}{l} Y\\ z\\ Greek \ sy\\ \alpha\\ \alpha_{\rm OSV}\\ \alpha_{\rm K}\\ \varepsilon\\ \varepsilon_{1}\\ \varepsilon_{2}\\ \mu\\ \rho\\ \tau_{\rm C}\\ \sigma\\ \Gamma\\ \Gamma\\ \Gamma_{\rm G,con}\\ \Gamma\\ \Gamma_{\rm G,V}\\ \Gamma_{\rm G,net} \end{array}$	defined in Eq. (19) axial location along the flow direction, m <i>mbols</i> void fraction void fraction at the onset of significant void void fraction for phase K pumping factor initial assumed void fraction at ONB initial assumed relative velocity at ONB dynamic viscosity, Pa s density, kg/m ³ condensation time, s surface tension, N/m vapor or liquid generation rate per unit mix- ture volume, kg/m ³ s vapor condensation rate in the bulk core, kg/m ³ s vapor production rate by the wall heating, kg/m ³ s net vapor generation rate in terms of the balance of the wall heating and the conden- ration in the bulk core, la_{2}/m^{3}
Y z $Greek sy \alpha \alpha_{GSV} \alpha_{K} \varepsilon \varepsilon_{1} \varepsilon_{2} \mu \rho \tau_{C} \sigma \Gamma \Gamma_{G,con} \Gamma_{G,V} \Gamma_{G,net}$	defined in Eq. (19) axial location along the flow direction, m <i>mbols</i> void fraction void fraction at the onset of significant void void fraction for phase K pumping factor initial assumed void fraction at ONB initial assumed relative velocity at ONB dynamic viscosity, Pa s density, kg/m ³ condensation time, s surface tension, N/m vapor or liquid generation rate per unit mix- ture volume, kg/m ³ s vapor condensation rate in the bulk core, kg/m ³ s vapor production rate by the wall heating, kg/m ³ s net vapor generation rate in terms of the balance of the wall heating and the conden- sation in the bulk core, kg/m ³ s
$\begin{array}{l} Y\\ z\\ Greek \ sy\\ \alpha\\ \alpha_{OSV}\\ \alpha_{K}\\ \varepsilon\\ \varepsilon_{1}\\ \varepsilon_{2}\\ \mu\\ \rho\\ \tau_{C}\\ \sigma\\ \Gamma\\ \Gamma\\ G, con\\ \Gamma\\ G, con\\ \Gamma\\ G, ret\\ \eta \end{array}$	defined in Eq. (19) axial location along the flow direction, m <i>mbols</i> void fraction void fraction at the onset of significant void void fraction for phase K pumping factor initial assumed void fraction at ONB initial assumed relative velocity at ONB dynamic viscosity, Pa s density, kg/m ³ condensation time, s surface tension, N/m vapor or liquid generation rate per unit mix- ture volume, kg/m ³ s vapor condensation rate in the bulk core, kg/m ³ s vapor production rate by the wall heating, kg/m ³ s net vapor generation rate in terms of the balance of the wall heating and the conden- sation in the bulk core, kg/m ³ s phase distribution parameter, $\eta = 0.5$ for
Y z $Greek sy \alpha \alpha_{OSV} \alpha_{K} \varepsilon \varepsilon_{1} \varepsilon_{2} \mu \rho \tau_{C} \sigma \Gamma \Gamma_{G,con} \Gamma_{G,V} \Gamma_{G,net} \eta$	defined in Eq. (19) axial location along the flow direction, m <i>mbols</i> void fraction void fraction at the onset of significant void void fraction for phase K pumping factor initial assumed void fraction at ONB initial assumed relative velocity at ONB dynamic viscosity, Pa s density, kg/m ³ condensation time, s surface tension, N/m vapor or liquid generation rate per unit mix- ture volume, kg/m ³ s vapor condensation rate in the bulk core, kg/m ³ s vapor production rate by the wall heating, kg/m ³ s net vapor generation rate in terms of the balance of the wall heating and the conden- sation in the bulk core, kg/m ³ s phase distribution parameter, $\eta = 0.5$ for bubbly flow, and $\eta = 0$ for other flow regime
$\begin{array}{l} Y\\ z\\ Greek \ sy\\ \alpha\\ \alpha_{OSV}\\ \alpha_{K}\\ \varepsilon\\ \varepsilon_{1}\\ \varepsilon_{2}\\ \mu\\ \rho\\ \tau_{C}\\ \sigma\\ \Gamma\\ \Gamma\\ G, con\\ \Gamma\\ G, con\\ \Gamma\\ G, ret\\ \eta\\ \theta\\ \end{array}$	defined in Eq. (19) axial location along the flow direction, m mbols void fraction void fraction at the onset of significant void void fraction for phase K pumping factor initial assumed void fraction at ONB initial assumed relative velocity at ONB dynamic viscosity, Pa s density, kg/m ³ condensation time, s surface tension, N/m vapor or liquid generation rate per unit mix- ture volume, kg/m ³ s vapor condensation rate in the bulk core, kg/m ³ s vapor production rate by the wall heating, kg/m ³ s net vapor generation rate in terms of the balance of the wall heating and the conden- sation in the bulk core, kg/m ³ s phase distribution parameter, $\eta = 0.5$ for bubbly flow, and $\eta = 0$ for other flow regime angle versus the gravity direction

$\delta_{ m th}$	thermal boundary layer thickness, m	con	condensation
Δho	$ ho_{\rm L} - ho_{\rm G}$	in	parameters at the location of the channel en-
$\Delta P_{\rm GO}$	friction pressure drop assuming all the mix-		trance
	ture is flowing as vapor	L	liquid
$\Delta P_{\rm LO}$	friction pressure drop assuming all the mix-	LG	values between vapor and liquid
	ture is flowing as liquid	G	vapor
Δz	mesh size, m	ONB	point of onset of nucleation boiling
		OSV	point of onset of significant void
Subscri	<i>ipts</i>	sat	saturated
0	the first node point in the two-phase flow	W	wall
	region		
В	bubbles		



Fig. 1. Void fraction and temperature development in a heated channel.

cooling [2], due to its ability to enhance higher heat dissipated rate from the device. Literature review [3] shows that the existing theoretical models on subcooled flow boiling focused mainly on the study of void growth distribution at pressurized water reactor at high pressures. The application of the existing models to the subcooled flow boiling at low pressures was found to be unsatisfactory, as reported by Hainoun et al. [3], and Zeitoun et al. [4].

In experimental investigation, Rogers et al. [5] performed the low-pressure subcooled boiling experiments to determine the void content at OSV. The results have shown that the void fraction at OSV was in the range of 5-10%. Bibeau et al. [6] measured the void fraction and wall temperatures for two annular channels at low pressures. They found that the void growth in this high subcooled region was significant, which was quite distinct from the characteristics at high-pressures. The author reported that for low-pressure subcooled flow boiling, the OSV was independent of the location of the first bubble detaching from the heating surface and the transition took place from the partial boiling to the fully developed boiling. So far most of the measurements were performed for vertical up-flow configuration. Little investigation was performed on void growth in vertical down-flow [7].

In mathematical modeling two approaches were proposed to calculate the void evolvement in the subcooled flow boiling, one was the profile-fit model, the other was the mechanistic model. It is noted that the profile-fit models do not attempt to model the mechanism of the subcooled boiling, in which the effect of buoyancy force and the detachment mechanism in the determination of void content are ignored. This model is usually based on a fit to uniform axial heat flux data. The prediction of the subcooled void distribution for non-uniform axial heat flux is questionable, as reported by Levy [8] and Staub [9].

Hainoun et al. [3] proposed a vapor generation model to simulate the subcooled flow boiling. The numerical predictions compared reasonable well with the experiment data. A mechanistic model was developed by Zeitoun et al. [4] to predict the axial void fraction profile in low-pressure subcooled flow boiling, in which the effect of buoyancy force was not considered. This buoyancy force effect will become significant at low-flow velocity in vertical down-flow configuration. The present investigation is motivated by the need to model the low-pressure subcooled flow boiling in the cooling of electronic devices operating at low-flow velocity. A one-dimensional, non-equilibrium two-fluid model is developed. The two-phases are modeled using the separated equations accounting for the interfacial forces between the phases. The model accounts for the flow direction in both the vertical upward and downward configurations and flow pattern transitions.

2. Mathematical models

2.1. Governing equations

Referring to Fig. 1, the subcooled liquid enters the gap channel formed by two infinity plates with the gap of δ . The bottom wall is being heated, while the upper wall is adiabatic or heated. The flow is considered to be one-dimensional with accounting for the average parameter in the height direction while the width direction is infinity. Heating causes the onset of boiling taking place somewhere downstream of the entrance. In the two-phase region, formulation of the general conservation equations of mass, momentum and energy was presented by Ishii and Mishima [10]. For the steady state with negligible kinetic and potential energy, the conservation equations are reduced to the following five equations. It is noted that the following conservation equations are general and are valid for the low pressure and mass flux operation ranges.

• Phase mass equations

$$\frac{\partial}{\partial z}(\alpha \rho_{\rm G} U_{\rm G}) = \Gamma_{\rm G} \tag{1}$$

$$\frac{\partial}{\partial z}[(1-\alpha)\rho_{\rm L}U_{\rm L}] = \Gamma_{\rm L} \tag{2}$$

• Phase momentum equations

$$\frac{\partial}{\partial z} (\alpha \rho_{\rm G} U_{\rm G}^2) + \alpha \frac{\partial P}{\partial z} + \alpha \rho_{\rm G} g \cos(\theta)$$

= $-F_{\rm WG} - F_{\rm LG} - F_{\rm GI}$ (3)

$$\frac{\partial}{\partial z} [(1-\alpha)\rho_{\rm L}U_{\rm L}^2] + (1-\alpha)\frac{\partial P}{\partial z} + (1-\alpha)\rho_{\rm L}g\cos(\theta)$$
$$= -F_{\rm WL} + F_{\rm LG} - F_{\rm LI} \tag{4}$$

• Mixture energy equation

$$\frac{\partial}{\partial z}(\alpha \rho_{\rm G} U_{\rm G} h_{\rm G} + [1 - \alpha] \rho_{\rm L} U_{\rm L} h_{\rm L}) = \frac{q_{\rm W} P_{\rm h}}{A}$$
(5)

It is assumed that the wall shear stress contributed by the vapor phase (F_{WG}) is negligible [11]. Note that $\Gamma_{\rm G} + \Gamma_{\rm L} = 0. q_{\rm W}$ is the applied wall heat flux, $P_{\rm h}$ is the heated perimeter and A is the flow cross-section area of the channel. $P_{\rm h}$ is $\pi D_{\rm i}$ for annular channels with the heating on the inner wall surface. The liquid density $\rho_{\rm L}$ is the functions of the pressure and enthalpy.

$$\rho_{\rm L} = \rho_{\rm L}(P, h_{\rm L}) \tag{6}$$

The vapor phase is assumed to be saturated thus the vapor density and the enthalpy are only depended on the pressure.

$$\rho_{\rm G} = \rho_{\rm G,sat}(P) \tag{7}$$

$$h_{\rm G} = h_{\rm G,sat}(P) \tag{8}$$

Eqs. (1)–(5) contain five unknowns, α , *P*, *U*_G, *U*_L, *h*_L. The liquid temperature is known from the liquid enthalpy $h_{\rm L}$ and pressure *P*.

2.2. The determination of the interfacial terms

2.2.1. Interfacial drag force between the two-phases

Interfacial drag force between the two phases F_{LG} is modeled as [11]

$$F_{\mathrm{LG}} = \frac{2C_{\mathrm{FI}}}{D_{\mathrm{h}}} \sqrt{\alpha} \rho_{\mathrm{G}} (U_{\mathrm{G}} - U_{\mathrm{L}}) \mid U_{\mathrm{G}} - U_{\mathrm{L}} \mid$$
$$+ C' \alpha \rho_{\mathrm{L}} U_{\mathrm{G}} \frac{\mathrm{d}(U_{\mathrm{G}} - U_{\mathrm{L}})}{\mathrm{d}z}$$
(9)

where C' is a virtual mass coefficient, taken as C' = 0.5 for bubbly flow and C' = 0 for other flow regimes. The interfacial friction factor $C_{\rm FI}$ is taken as

$$C_{\rm FI} = \begin{cases} C_{\rm D} \sqrt{\alpha} (1-\alpha)^{-1.7} \frac{\rho_{\rm L}}{\rho_{\rm G}} \frac{D_{\rm h}}{2R_{\rm B}} \\ \text{bubbly flow } (\alpha \leqslant 0.25) \\ 0.005(1+75(1-\alpha)) \\ \text{annular flow } (\alpha \geqslant 0.8) \end{cases}$$
(10)

In the churn turbulent flow with medium void fraction between the bubbly and annular flow, $C_{\rm FI}$ is interpolated linearly with void fraction between the two values given in Eq. (10). The drag coefficient for a single bubble $C_{\rm D}$, in Eq. (10), depends on the bubble Reynolds number $Re_{\rm B}$

$$C_{\rm D} = \begin{cases} \frac{24}{Re_{\rm B}} (1 + 0.15Re_{\rm B}^{0.687}) & Re_{\rm B} < 1000\\ 0.44 & Re_{\rm B} \ge 1000 \end{cases}$$
(11)

where the bubble Reynolds number $Re_{\rm B}$ is defined as

$$Re_{\rm B} = \frac{2\rho_{\rm L}R_{\rm B}(1-\alpha) \mid U_{\rm G} - U_{\rm L} \mid}{\mu_{\rm L}}$$
(12)

Note that F_{LG} in Eq. (9) is positive for vertical upward flow ($U_G > U_L$), and negative for vertical downward flow ($U_G < U_L$).

2.2.2. Shear stress between the liquid phase and the tube wall

The wall liquid friction F_{WL} is modeled by the Chisholm's correlation [12], since such correlation fits the advanced empirical correlation curves of Baroczy quite well and accounts for the effect of mass flux on the friction pressure gradient. The correlation is expressed by the following set of equations:

$$F_{\rm WL} = \lfloor 1 + (Y^2 - 1)(Bx^{(2-n)/2}(1-x)^{(2-n)/2} + x^{2-n}) \rfloor \Delta P_{\rm LO}$$
(13)

$$\Delta P_{\rm LO} = \frac{4}{D_{\rm h}} f_{\rm LO} \frac{G^2}{2\rho_{\rm L}} \tag{14}$$

where $\Delta P_{\rm LO}$ is the single phase friction pressure drop which would exist if the total mass flow of two phase mixture flowed as liquid phase only, *n* is the power in the friction factor–Reynolds number relationship (n = 0.25 for the Blasius equation). *Y* is a property coefficient defined by the square root of the ratio between the pressure gradient due to friction if the total mixture flows as vapor only and that if the total mixture flows as liquid only, i.e.,

$$Y = \left(\frac{\Delta P_{\rm GO}}{\Delta P_{\rm LO}}\right)^{0.5} = \left(\frac{f_{\rm GO}\rho_{\rm L}}{f_{\rm LO}\rho_{\rm G}}\right)^{0.5} \tag{15}$$

The coefficient B in Eq. (13) is given by

$$B = \frac{CY - 2^{2-n} + 2}{Y^2 - 1} \tag{16}$$

where

$$C = \frac{U_{\rm L}}{U_{\rm G}} \sqrt{\frac{\rho_{\rm L}}{\rho_{\rm G}}} \left(1 + \frac{U_{\rm G}^2}{U_{\rm L}^2} \frac{\rho_{\rm G}}{\rho_{\rm L}} \right) \tag{17}$$

The true vapor mass quality x can be calculated as

$$x = \frac{1}{1 + \frac{1-\alpha}{\alpha} \frac{\rho_{\rm L}}{\rho_{\rm G}} \frac{U_{\rm L}}{U_{\rm G}}} \tag{18}$$

In Eq. (14) f_{LO} is the single-phase friction coefficient determined from

$$f_{\rm LO} = \frac{16}{Re_{\rm LO}} \text{ for } Re_{\rm LO} = \frac{GD_{\rm h}}{\mu_{\rm L}} \leqslant 2000 \tag{19}$$

$$f_{\rm LO} = 0.079 R e_{\rm LO}^{-0.25}$$
 for $R e_{\rm LO} = \frac{G D_{\rm h}}{\mu_{\rm L}} > 2000$ (20)

In Eq. (15) $f_{\rm GO}$ is determined from equations similar to Eqs. (19) and (20), but involving the vapor properties.

2.2.3. Determination of F_{GI} and F_{LI}

The momentum exchange between the phases, F_{GI} and F_{LI} , due to the mass exchange, are modeled as:

$$F_{\rm GI} = \eta (U_{\rm G} - U_{\rm L}) \Gamma_{\rm G} \tag{21}$$

$$F_{\rm LI} = (1 - \eta)(U_{\rm L} - U_{\rm G})\Gamma_{\rm L} \tag{22}$$

 η is the phase distribution factor, $\eta = 0.5$ for bubbly flow, and $\eta = 0$ in other flow regime.

2.3. Vapor generation rate

After ONB, bubbles appearing on the heating surface may condense in the bulk flow as they recede from the surface. The net amount of vapor generation rate is determined by the difference between the vapor generation rate at the wall and the condensation rate in the bulk. A correlation by Bergels et al. [13] is used to determine the wall overheating at which the first nuclei is activated

$$T_{\rm W} - T_{\rm sat} = \frac{5}{9} \left(\frac{q_{\rm W}}{1100} P^{-1.156} \right)^{0.463 P^{0.0234}}$$
(23)

The left hand of the above equation is the wall superheating. *P* is the pressure in bar. q_W has the unit of W/m².

In the subcooled region, the wall heat flux can be divided into three components, i.e. the vapor generation term q_V , single phase forced convection fraction, and the "pumping effect", q_p due to the agitation of the thermal boundary layer caused by the bubble growth-collapse cycle. The last two terms are combined together to contribute the sensible heating of the bulk liquid.

$$q_{\rm W} = q_{\rm V} + C_1 \dot{h}_{\rm sp} (T_{\rm W} - T_{\rm L}) + q_{\rm p} \tag{24}$$

where C_1 accounts for the portion of the heating surface which is not cover by bubbles. C_1 is dependent on the void fraction. The heating surface is not directly accessible to liquid as the void content increases since more bubbles cover the heating surface. Hainoun et al. [3] suggested that C_1 can be expressed as:

$$C_{1} = 1 - \frac{\pi}{16} \frac{\alpha}{\alpha_{OSV}} \quad \text{for } \alpha \leq \frac{16\alpha_{OSV}}{\pi}$$

$$C_{1} = 0 \qquad \qquad \text{for } \alpha > \frac{16\alpha_{OSV}}{\pi}$$
(25)

where α_{OSV} is the void content at OSV.

 h_{sp} is the single-phase heat transfer coefficient and the wall temperature T_{W} is predicted by Shah [14].

Define pumping factor as the ratio between the pumping component and the vapor component, $\varepsilon = \frac{q_P}{q_V}$. Thus q_V is given as:

$$q_{\rm V} = \frac{q_{\rm W} - C_1 h_{\rm sp} (T_{\rm W} - T_{\rm L})}{1 + \varepsilon} \tag{26}$$

Introduce another coefficient C_2 to relate the pump factor as

$$C_2 = \frac{1}{1+\varepsilon} \tag{27}$$

Eq. (26) is rewritten as

$$q_{\rm V} = C_2 (q_{\rm W} - C_1 \tilde{h}_{\rm sp} [T_{\rm W} - T_{\rm L}])$$
(28)

The pumping factor can be calculated from Zeitoun and Shoukri [4] as

$$\varepsilon = \frac{3}{4} \frac{\rho_{\rm L} C_{\rm PL} (T_{\rm W} - T_{\rm L})}{\rho_{\rm G} h_{\rm LG}} \frac{\delta_{\rm th}}{2R_{\rm B}}$$
(29)

where the thermal boundary layer thickness δ_{th} is defined as

$$\delta_{\rm th} = \frac{k_{\rm L}(T_{\rm W} - T_{\rm L})}{q_{\rm W}} \tag{30}$$

Alternatively, Yang and Weisman [15] correlated the pumping factor based on their experimental data as

$$\varepsilon = 3 \frac{h_{\rm L,sat} - h_{\rm L}}{h_{\rm LG}} \tag{31}$$

Note that, Eq. (31) is only valid for R113, which needs more verification before it is extended to other working fluids.

The coefficient C_2 can be determined once ε is established. Alternatively, the C_2 expression developed by Hainoun et al. [3] can be used

$$C_2 = 2C_{\rm EV} \left(\frac{T_{\rm W} - T_{\rm sat}}{T_{\rm W} - T_{\rm L}}\right)^2 \tag{32}$$

where $C_{\rm EV}$ is an evaporation parameter with a value of about 0.5.

Hence the vapor production rate on the wall surface is given as

$$\Gamma_{\rm G,V} = \frac{q_{\rm V} P_{\rm h}}{A h_{\rm LG}} \tag{33}$$

2.3.1. Bubble condensation rate

Hainoun et al. [3] assumed that bubble condensation is dependent on the Jacob number. Heat transfer at the phase boundary largely determines condensation when the Jacob number is less than 80. Inertia effects are dominant if the Jacob number is larger than 100. In transition region (80 < Ja < 100) both the heat transfer and the inertia effects are of significance. The inertia-controlled condensation is written as

$$\Gamma_{\rm G,con} = C_{\rm con} \rho_{\rm G} \frac{\alpha}{\tau_C} \tag{34}$$

where $\tau_{\rm C}$ is the condensation time after Rayleigh.

In the heat transfer dominant region, the condensation rate is modeled in terms of the bulk Reynolds number as

$$\Gamma_{\rm G,con} = C_{\rm con} 3.6 \frac{\alpha}{d_{\rm BA}^2} \rho_{\rm G} a N u_1 J a \quad \text{for } Re < 10^4 \tag{35}$$

$$\Gamma_{\rm G,con} = C_{\rm con} 3.6 \frac{\alpha}{d_{\rm BA} D_{\rm h}} \rho_{\rm G} a N u_2 J a \quad \text{for } Re > 3 \times 10^4$$
(36)

 $C_{\rm con}$ has the empirical value of 0.16 through comparing with the experimental data. The determination of $\tau_{\rm C}$, $d_{\rm BA}$, Nu_1 and Nu_2 can be found in Hainoun et al. [3].

Hence the net vapor generation rate is determined by the difference between the vapour generation rate at the wall and the condensation rate in the bulk

$$\Gamma_{\rm G,net} = \frac{q_{\rm V} P_{\rm h}}{A h_{\rm LG}} - \Gamma_{\rm G,con} \tag{37}$$

3. Solution procedure

With the assumption that the vapor phase is saturated, thus the vapor density and enthalpy are dependent on pressure, the differential terms $\frac{\partial \rho_G}{\partial z}$, and $\frac{\partial h_G}{\partial z}$ can be replaced by the differential terms of $\frac{\partial P}{\partial z}$ by

$$\frac{\partial \rho_{\rm G}}{\partial z} = \frac{\partial \rho_{\rm G}}{\partial P} \frac{\partial P}{\partial z} = \frac{1}{a_{\rm G}^2} \frac{\partial P}{\partial z} \tag{38}$$

$$\frac{\partial h_G}{\partial z} = \frac{\partial h_G}{\partial P} \frac{\partial P}{\partial z} \tag{39}$$

The liquid density is dependent on pressure and enthalpy. Thus $\frac{\partial \rho_1}{\partial z}$ can be replaced by:

$$\frac{\partial \rho_{\rm L}}{\partial z} = \frac{\partial \rho_{\rm L}}{\partial h_{\rm L}} \Big|_{P} \frac{\partial h_{\rm L}}{\partial z} + \frac{\partial \rho_{\rm L}}{\partial P} \Big|_{h_{\rm L}} \frac{\partial P}{\partial z} \tag{40}$$

Substituting Eqs. (38)-(40) into the partial differential Eqs. (1)-(5), we obtained:

$$\rho_{\rm G} U_{\rm G} \frac{\partial \alpha}{\partial z} + \frac{\alpha U_{\rm G}}{a_{\rm G}^2} \frac{\partial P}{\partial z} + \alpha \rho_{\rm G} \frac{\partial U_{\rm G}}{\partial z} = \Gamma_{\rm G}$$
(41)

$$-\rho_{\rm L}U_{\rm L}\frac{\partial\alpha}{\partial z} + (1-\alpha)U_{\rm L}\frac{\partial\rho_{\rm L}}{\partial P}\Big|_{h_{\rm L}}\frac{\partial P}{\partial z} + (1-\alpha)\rho_{\rm L}\frac{\partial U_{\rm L}}{\partial z} + (1-\alpha)U_{\rm L}\frac{\partial\rho_{\rm L}}{\partial h_{\rm L}}\Big|_{P}\frac{\partial h_{\rm L}}{\partial z} = \Gamma_{\rm L}$$
(42)

$$\alpha \rho_{\rm G} U_{\rm G} \frac{\partial U_{\rm G}}{\partial z} + \alpha \frac{\partial P}{\partial z} + \alpha \rho_{\rm G} g \cos(\theta) = -F_{\rm LG} - F_{\rm GI} \quad (43)$$

$$(1 - \alpha)\rho_{\rm L}U_{\rm L}\frac{\partial U_{\rm L}}{\partial z} + (1 - \alpha)\frac{\partial P}{\partial z} + (1 - \alpha)\rho_{\rm L}g\cos(\theta)$$

= $-F_{\rm WL} + F_{\rm LG} - F_{\rm LI}$ (44)

$$\alpha \rho_{\rm G} U_{\rm G} \frac{\partial h_{\rm G}}{\partial P} \frac{\partial P}{\partial z} + (1 - \alpha) \rho_{\rm L} U_{\rm L} \frac{\partial h_{\rm L}}{\partial z}$$
$$= \frac{q_{\rm W} P_{\rm h}}{A} - \Gamma_{\rm G} (h_{\rm G} - h_{\rm L})$$
(45)

Eqs. (41)–(45) can be expressed as Eq. (46) by choosing α , *P*, *U*_G, *U*_L, *h*_L as the dependent variables

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$$\begin{bmatrix} \rho_{\rm G} U_{\rm G} & \frac{\alpha U_{\rm G}}{a_{\rm G}^2} & \alpha \rho_{\rm G} & 0 & 0\\ -\rho_{\rm L} U_{\rm L} & (1-\alpha) U_{\rm L} \frac{\partial \rho_{\rm L}}{\partial P} \Big|_{h_{\rm L}} & 0 & (1-\alpha) \rho_{\rm L} & (1-\alpha) U_{\rm L} \frac{\partial \rho_{\rm L}}{\partial h_{\rm L}} \Big|_{P} \\ 0 & \alpha & \alpha \rho_{\rm G} U_{\rm G} & 0 & 0\\ 0 & (1-\alpha) & 0 & (1-\alpha) \rho_{\rm L} U_{\rm L} & 0\\ 0 & \alpha \rho_{\rm G} U_{\rm G} \frac{\partial h_{\rm G}}{\partial P} & 0 & 0 & (1-\alpha) \rho_{\rm L} U_{\rm L} \end{bmatrix}_{i-1} \begin{bmatrix} \frac{\partial \alpha}{\partial z} \\ \frac{\partial P}{\partial z} \\ \frac{\partial U_{\rm G}}{\partial z} \\ \frac{\partial U_{\rm L}}{\partial z} \\ \frac{\partial H_{\rm L}}{\partial z} \\ \frac{\partial h_{\rm L}}{\partial z} \end{bmatrix}_{i} = \begin{bmatrix} B_{1} \\ B_{2} \\ B_{3} \\ B_{4} \\ B_{5} \end{bmatrix}_{i-1}$$
(46)

Here

$$B_{1} = \Gamma_{G,\text{net}}$$

$$B_{2} = -\Gamma_{G,\text{net}}$$

$$B_{3} = -F_{LG} - F_{GI} - \alpha \rho_{G} g \cos(\theta)$$

$$B_{4} = -F_{WL} + F_{LG} - F_{LI} - (1 - \alpha) \rho_{L} g \cos(\theta)$$

$$B_{5} = \frac{q_{W} P_{h}}{A} - \Gamma_{G,\text{net}} (h_{G,\text{sat}} - h_{L})$$

$$(47)$$

Eq. (46) was solved using Runge–Kutta or Euler method for small mesh size.

3.1. Boundary condition

To start the computation, an initial void fraction (ε_1) and bubble relative velocity (ε_2) are used. The calculation shows that the range of $\varepsilon_1=10^{-3}-10^{-5}$ and $\varepsilon_2=10^{-2}-10^{-4}$ has no influence on the calculated void fraction. Note that ε_2 is positive for vertical up-flow, and negative for the vertical down-flow.

The boundary conditions of the two-phase at $z = z_{L_{sp}}$ are

$$\alpha_{0} = \varepsilon_{1}$$

$$P_{0} = P_{in} - \frac{4L_{sp}}{D_{h}} f_{LO} \frac{G^{2}}{2\rho_{L,in}} (P_{in} \text{ specified})$$

$$U_{G,0} = U_{L,0} + \varepsilon_{2}$$

$$U_{L,0} = \frac{G}{\rho_{L,ONB}} (G \text{ specified})$$

$$h_{L,0} = h_{L,ONB}$$

$$\left. \right\}$$

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Integration was performed from the ONB to the channel exit using the Gauss–Seidel iteration technique to solve the linear Eq. (46). Initially larger mesh sizes, corresponding to a small number of node points N are used. Then N is increased gradually to check its effect on the exit void fraction. Such process stopped until a very stable exit void fraction is reached. For most of our calculations, N = 50–100 has enough accuracy.

4. Results and discussion

4.1. Sensitivity analysis of coefficients C_1 and C_2

To validate the proposed model, comparisons have been made with the available experimental data published by Zeitoun and Shoukri [4]. Sensitivity analyses of coefficients C_1 and C_2 in the vapor generation equation were conducted. Curve 1 in Fig. 2 is plotted using $C_1 = 1.0$. Since α_{OSV} is in the range of 0.05–0.1 as reported by Rogers et al. [5], curves 2 and 3 are produced using Eq. (25) with α_{OSV} of 0.05 and 0.1, respectively. It is seen from Fig. 2 that the calculated void fractions are insensitive to the C_1 coefficient. The differences among the three curves can only be identified near the channel exit. The results indicated that under low-fluid velocity the single phase heat transfer fraction is insignificant in vapour generation. The void fraction is insensitive to the fraction of the heating surface covered by the fluid.

Fig. 3 shows the influence of C_2 on the void fraction. The result indicated that the pumping factor ε developed by Yang and Weisman [15] (curve 3) over-predicts the void fraction. Since the correlation was developed from the experimental data of R113, it is not suitable for water-steam system. The pumping factor developed by Zeitoun and Shoukri [4] (curve 1) also over-predicts the void fraction. Note that the C_2 coefficient by Hainoun et al. [3] (curve 2 using Eq. (32)) matches the experimental data very well. Based on the above analysis, the following coefficients were used in the subsequent void fraction modeling.

$$C_1 = 1$$

$$C_2 = 2C_{\rm EV} \left(\frac{T_{\rm W} - T_{\rm sat}}{T_{\rm W} - T_{\rm L}}\right)^2$$



Fig. 2. Effect of C_1 coefficient on the void fraction.



Fig. 3. Effect of C_2 coefficient on the void fraction.

4.2. Comparisons with the experimental data

To validate the proposed model, comparisons have been made with available experimental data by Donevski and Shoukri [16], Rogers et al. [5], and Zeitoun and Shoukri [4], Bibeau and Salcudean [7]. Their experimental set-up and flow conditions are summarized in Table 1. The experimental parameters cover the follow ranges: pressure of 1–2 bar, mass flux of 70–500 kg/m², and wall heat flux of 300–1000 kW/m².

Figs. 4 and 5 show that the proposed theoretical void fraction distributions agree well with the experiment data presented by Zeitoun et al. [4] and Rogers et al. [5] in vertical up-flow configuration.

Fig. 6 shows a comparison of the void fraction distribution along the tube with experimental results reported by Donevski et al. [16]. In the reported experiment, an adiabatic section was maintained after 0.4 m measured from the inlet. Again good agreement was obtained.

4.3. Comparison between the vertical up-flow and down-flow

Fig. 7 shows the comparisons of void fractions for vertical up-flow and vertical down-flow. The good agreement between predicted value and experimental data



Fig. 4. Comparisons of model prediction with experimental data by Zeitoun and Shoukri [4].



Fig. 5. Comparisons of the model prediction with experimental data by Rogers et al. [5].

presented by Bibeau et al. [7] indicates that the present model is applicable to both vertical up-flow and downflow situation. The results show that for the same flow condition, higher void fraction prevails for vertical down-flow than that for vertical up-flow. The numerical results also show that OSV occurs early for vertical down-flow than that of up-flow. This is due to the reason that for vertical down-flow, the buoyancy force is opposite to the bulk flow hence a lower vapor velocity

Table 1

Various experimenta	l set-up and	flow co	ondition for	void	fraction	measurement
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Authors	Annular gap dimension (mm)	Channel length (mm)	Flow direction	Pressure (bar)	Mass flux (kg/m ² s)	Heat flux (kw/m ²)	Inlet subcooling (°C)
Donevski and Shoukri [16]	25.0 mm OD, 12.7 mm ID	420	Vertical up-flow	1.687–1.735	420–430	576–594	30
Rogers et al. [5]	30.9 mm OD, 13.1 mm ID	480, 600	Vertical up-flow	1.50-1.55	70–450	300-1200	18–51
Zeitoun and Shoukri [4]	25.4 mm OD, 12.7 mm ID	300	Vertical up-flow	1.17–1.68	252.8-403.0	487.9–603.2	16.6–20.1
Bibeau and Salcudean [7]	21.8 mm OD, 12.7 mm ID	480	Vertical down-flow	1.55	220-450	300–900	10-85



Fig. 6. Comparisons of model prediction with experimental data by Donevski and Shoukri [16].



Fig. 7. Comparisons of model prediction with experimental data for both verticals up and down flow by Bibeau and Salcudean [7].



Fig. 8. Two phase velocity distribution against the thermodynamic quality.

is predicted. Fig. 8 shows the variation of liquid phase and vapor phase velocities against the quality. As the buoyancy force is opposite to the flow, vapor is difficult to move into the downward bulk flow hence vapor residing in the channel and a larger void fraction is resulted.

5. Conclusions

A one-dimensional, non-equilibrium two-fluid model has been developed for the predictions of low-pressure subcooled flow boiling. The model has been validated by the available experimental data for both vertical up-flow and down-flow.

The simulated results show that at low pressure the void fraction is insensitive to the fraction of the heating surface covered by the fluid. The predicted results highlight that buoyancy force plays an important role on the void fraction evolvement, especially at low velocity for vertical down-flow.

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